## In a nutshell: Neumann and insulated boundary conditions

Given a second order linear ordinary differential equation with constant coefficients

$$a_2(x)u^{(2)}(x) + a_1(x)u^{(1)}(x) + a_0(x)u(x) = g(x),$$

two spatial boundary points [*a*, *b*] and two boundary conditions: either Dirichlett,  $u(a) = u_a$  and  $u(b) = u_b$ ; or Neumann:  $u^{(1)}(a) = u_a^{(1)}$  and  $u^{(1)}(b) = u_b^{(1)}$ . Recall that if a constant has a derivative, that indicates that the constant represents a slope; it does not suggest we are taking the derivative of that constant. An insulated boundary condition is when we have a Neumann condition and the derivative is set to zero.

Parameters:

- *n* The number of sub-intervals into which [*a*, *b*] will be divided.
- 1. Set  $h \leftarrow \frac{b-a}{n}$  and  $x_k \leftarrow a + kh$  noting that  $x_n = b$ .
- 2. For *k* going from 1 to n 1, assign the following:

$$p_k \leftarrow 2a_2(x_k) - a_1(x_k)h$$
$$q_k \leftarrow -4a_2(x_k) + 2a_0(x_k)h^2$$
$$r_k \leftarrow 2a_2(x_k) + a_1(x_k)h$$

If the linear ordinary differential equation has constant coefficients, all p, q and r values are equal to each other.

3. Create the system of n - 1 linear equations in n - 1 unknowns

$$\mathbf{A}\mathbf{u} = \begin{pmatrix} q_{1} & r_{1} & & & \\ p_{2} & q_{2} & r_{2} & & \\ p_{3} & q_{3} & r_{3} & & \\ & p_{4} & q_{4} & r_{4} & \\ & & \ddots & \ddots & \ddots & \\ & & & p_{n-2} & q_{n-2} & r_{n-2} \\ & & & & & q_{n-1} & q_{n-1} \end{pmatrix} \begin{pmatrix} u_{1} \\ u_{2} \\ u_{3} \\ u_{4} \\ \vdots \\ u_{n-2} \\ u_{n-1} \end{pmatrix} = \begin{pmatrix} 2g(x_{1})h^{2} \\ 2g(x_{2})h^{2} \\ 2g(x_{3})h^{2} \\ 2g(x_{3})h^{2} \\ \vdots \\ 2g(x_{n-1})h^{2} \\ 2g(x_{n-1})h^{2} \end{pmatrix} = \mathbf{g}$$

- 4. We modify the matrix *A* and the vector **g** as follows:
  - a. If the left-hand boundary condition is a Dirichlet condition, update  $g_1 \leftarrow g_1 p_1 u_a$ ;
  - b. otherwise, the left-hand boundary condition is a Neumann condition, so update:

i. 
$$a_{1,1} \leftarrow a_{1,1} + \frac{4}{3} p_1$$
  
ii.  $a_{1,2} \leftarrow a_{1,2} - \frac{1}{3} p_1$   
iii.  $g_1 \leftarrow g_1 + \frac{2}{3} p_1 u_a^{(1)} h$ 

- c. If the right-hand boundary condition is a Dirichlet condition, update  $g_{n-1} \leftarrow g_{n-1} r_{n-1}u_b$ ;
- d. otherwise, the right-hand boundary condition is a Neumann condition, so update:

i. 
$$a_{n-1,n-2} \leftarrow a_{n-1,n-2} - \frac{1}{3}r_{n-1}$$
  
ii.  $a_{n-1,n-1} \leftarrow a_{n-1,n-1} + \frac{4}{3}r_{n-1}$   
iii.  $g_{n-1} \leftarrow g_{n-1} - \frac{2}{3}r_{n-1}u_b^{(1)}h$ 

Note that the right-hand vector **g** is not updated for insulated boundary conditions.

- 5. Solve the updated system of linear equations  $A\mathbf{u} = \mathbf{g}$ .
- 6. The approximation of  $u(x_k)$  is  $u_k$  for k = 1, ..., n 1; and
  - a. If the left-hand boundary condition is Dirichlet,  $u(x_0) = u(a) = u_a$ ;
  - b. otherwise, the left-hand boundary condition is Neuman, so

$$u(x_0) = u(a) \approx -\frac{2}{3}u_a^{(1)}h + \frac{4}{3}u_1 - \frac{1}{3}u_2$$

- c. If the right-hand boundary condition is Dirichlet,  $u(x_n) = u(b) = u_b$ ;
- d. otherwise, the right-hand boundary condition is Neumann, so

$$u(x_n) = u(b) \approx \frac{2}{3} u_b^{(1)} h + \frac{4}{3} u_{n-1} - \frac{1}{3} u_{n-2}$$